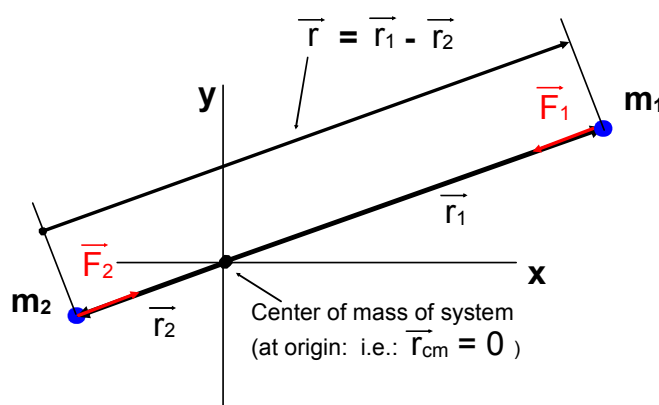


Setup for solving the "two body problem"

$$\vec{F}_1 = -\frac{Gm_1m_2}{r^2} \hat{e}_r \quad (\hat{e}_r = \frac{\vec{r}}{r})$$



Reduce 2-body problem to "motion under central force", in this case, "central force" will be Newton's inverse square law for gravity.

$$m_1\vec{r}_1 + m_2\vec{r}_2 = (m_1 + m_2)\vec{r}_{cm}$$

From definition of center-of-mass

$$\vec{r}_{cm} = 0$$

From setup

$$m_1\vec{r}_1 + m_2\vec{r}_2 = 0$$

$$\vec{r}_2 = -\frac{m_1}{m_2}\vec{r}_1 \quad \text{also } \vec{r} = \vec{r}_1 - \vec{r}_2 \quad \text{Eliminate } \vec{r}_2$$

$$\vec{r} = \vec{r}_1 + \frac{m_1}{m_2}\vec{r}_1 = \vec{r}_1\left(1 + \frac{m_1}{m_2}\right) = \vec{r}_1\left(\frac{m_1 + m_2}{m_2}\right)$$

Setup the D.E. (from Newton's 2nd law) of motion for \mathbf{m}_1 relative to c.m.:

$$m_1 \ddot{\vec{r}}_1 = - \frac{G m_1 m_2}{r^2} \hat{e}_r$$

note: $\vec{r} = \vec{r}_1 \left(\frac{m_1 + m_2}{m_2} \right)$
 $\dot{\vec{r}} = \dot{\vec{r}}_1 \left(\frac{m_1 + m_2}{m_2} \right)$
 $\ddot{\vec{r}} = \ddot{\vec{r}}_1 \left(\frac{m_1 + m_2}{m_2} \right) \Rightarrow \ddot{\vec{r}}_1 = \frac{m_2}{m_1 + m_2} \ddot{\vec{r}}$

Replace $\ddot{\vec{r}}_1$ with $\frac{m_2}{m_1 + m_2} \ddot{\vec{r}}$ (In the D.E. above.)

$$\frac{m_1 m_2}{m_1 + m_2} \ddot{\vec{r}} = - \frac{G m_1 m_2}{r^2} \hat{e}_r$$

let $\mu = \frac{m_1 m_2}{m_1 + m_2} \equiv$ "reduced mass"

$$\mu \ddot{\vec{r}} = - \frac{G m_1 m_2}{r^2} \hat{e}_r \quad \text{D.E. in terms of } \vec{r}$$

Or finally write D.E. in terms of \mathbf{m}_1 and its acceleration relative to \mathbf{m}_2 :

$$m_1 \ddot{\vec{r}} = - \frac{k}{r^2} \hat{e}_r \quad \text{where } k = G(m_1 + m_2)m_1$$